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# INTRODUCTION

Goal: Identify objects in a large collection of unlabelled images.

#### Motivation:

- Automatically analyze image collections.
- Obtain free image annotations.

## Recent Prior Work:

Find objects that are frequently appearing visual patterns [8, 66, 67] using a sequential algorithm:

$$\max_{x,e} \sum_{p=1}^{''} \sum_{q \in \mathcal{N}(p)} e_{pq} x_p^T S_{pq} x_q$$

s.t. 
$$\sum_{k=1}^{r} x_p^k \leq \nu$$
 and  $\sum_{q \neq p} e_{pq} \leq \tau \quad \forall p.$ 

Limitations: Does not scale well, relies on supervised features for good performance.

### CONTRIBUTIONS

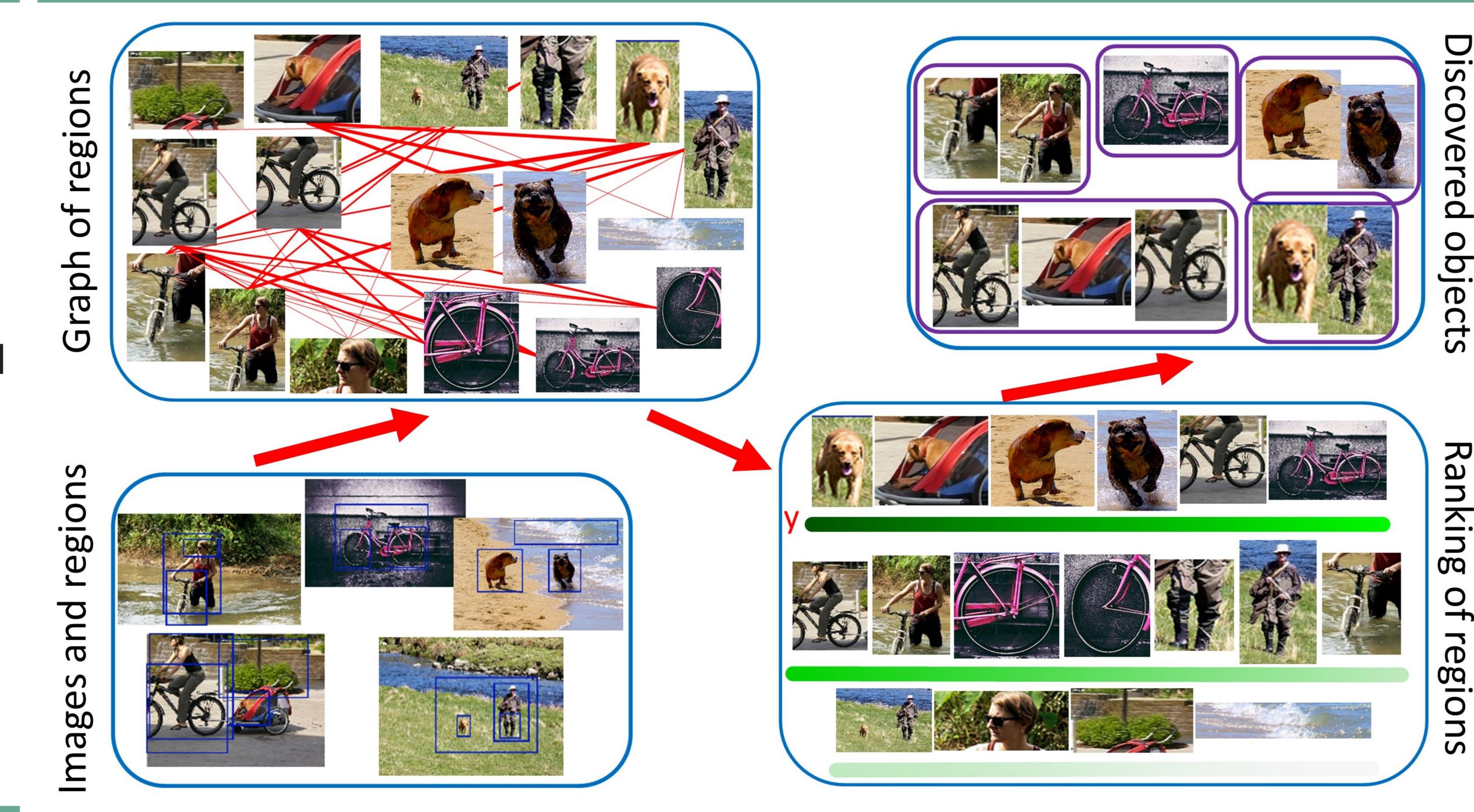
- We formulate UOD as a ranking problem to:
  - Is allow parallel and distributed solutions.
  - scale UOD up to datasets 87 times larger than those considered in the previous work.
  - improve multi-object discovery performance by up to 32% according to Average Precision.
- We demonstrate the first viable pipeline for completely unsupervised object discovery using self-supervised features.

**References:** [8] Cho et al., CVPR'15; [14] Feng et al., ICCV'11; [31] Kim et al., CVPR'08; [32] Kim et al., NIPS'09; [33] Kim et al., CVPR'12; [35] Krasin et al., 2017; [37] Langville et al., Internet Mathematics, 2004; [42] Lin et al., ECCV'14; [48] Page et al., 1999; [66] Vo et al., CVPR'19; [67] Vo et al., ECCV'20; [68] Mises et al., 1929; [71] Wei et al., PR'19; [73] Zhang et al., Trans. On Neural Networks, 2011; [74] Zhang et al., Applied Intelligence, 2009; [75] Zhang et al., ICCV'15; [82] Zhu et al., CVPR'12; [83] Zitnick et al., ECCV'14. **Acknowledgments:** This work was supported in part by the Inria/NYU collaboration, the Louis Vuitton/ENS chair on artificial intelligence and the French government under management of Agence Nationale de la Recherche as part of the "Investissements d'avenir" program, reference ANR19-P3IA-0001 (PRAIRIE 3IA Institute). Elena Sizikova was supported by the Moore-Sloan Data Science Environment initiative (funded by the Alfred P. Sloan Foundation and the Gordon and Betty Moore Foundation) through the NYU Center for Data Science. Huy V. Vo was supported in part by a Valeo/Prairie CIFRE PhD Fellowship. We thank Spyros Gidaris for providing the VGG16-based OBoW model. Finally, we thank anonymous reviewers for their helpful suggestions and feedback for the paper.

# Large-Scale Unsupervised Object Discovery Huy V. Vo<sup>1,2</sup>, Elena Sizikova<sup>3</sup>, Cordelia Schmid<sup>1</sup>, Patrick Pérez<sup>2</sup> and Jean Ponce<sup>1,3</sup>

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### **OVERVIEW**



### PROPOSED RANKING FORMULATIONS

Input: Symmetric weight matrix	Pag
W, # of nodes $N$ .	$\triangleright$ N
Output: Nodes' importance.	
A node is important if it is	⊳ Pa wi
well-connected and its neighbors	pe
are important.	⊳ Pa
Quadratic optimization (Q):	ei
Importance score:	Hył
$y_i \in [0, 1], y = (y_1, y_2, \dots, y_N)^t.$	$\triangleright Q$
> Total importance of edges of node $i$ :	pe ⊳ I (
$c_i = \sum_j y_i W_{ij} y_j.$ $\triangleright$ Optimization:	
$y^* = \underset{\substack{y \ge 0, \ y\  \le 1}}{\operatorname{argmax}} \sum_i c_i = y^t Wy.$	(Q),
$\triangleright y^*$ is the largest eigenvector of $W$ .	eige distr
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**geRank (P)** [37,48]: Nodes are states of a Markov chain. Transition matrix:  $A = W \operatorname{diag}({}_{M}^{t}W)^{-1}$ . PageRank matrix:  $P = (1 - \beta)A + \beta u_N^t$ with  $\beta \in [0, 1]$  and  $u \ge 0$  is the personalized vector. PageRank vector: The largest eigenvector of P. **/brid formulation (LOD)**: Q's solution is good. Using Q to build a personalized vector u(Q).

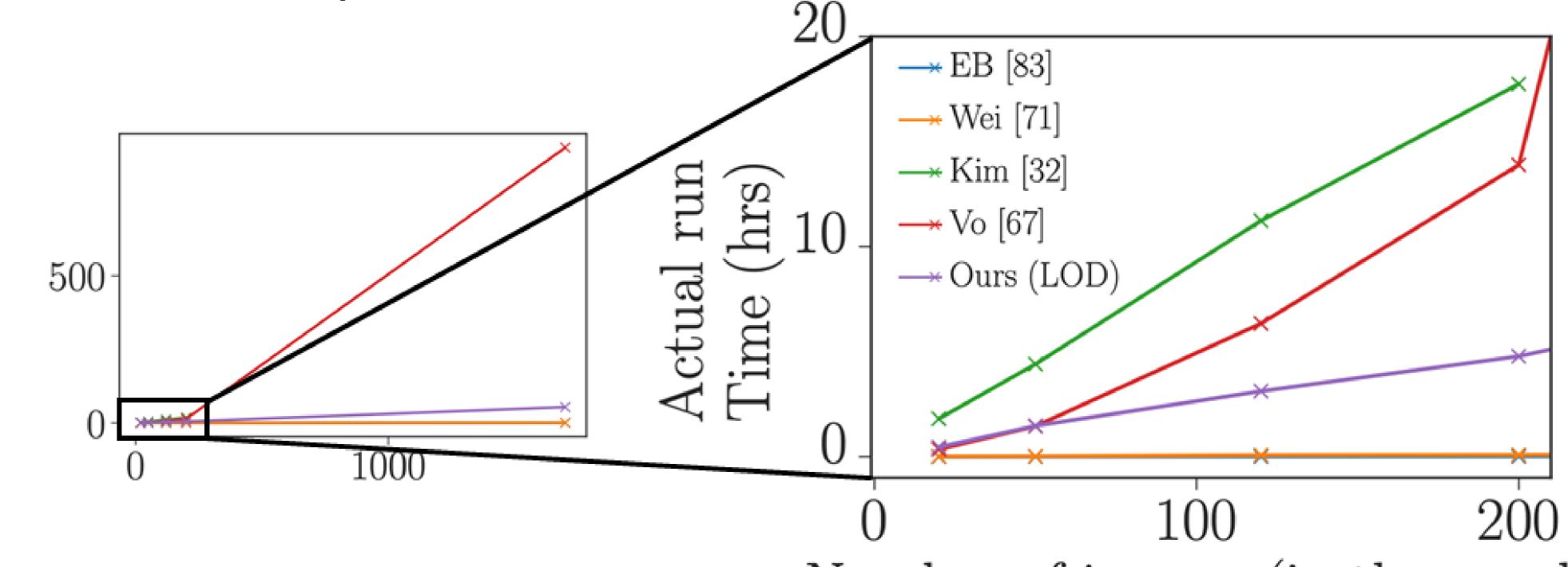
\_OD: Personalized PageRank with  $\mathsf{P} = (1 - \beta)\mathsf{A} + \beta \mathsf{u}(\mathsf{Q})_{\mathsf{I}_{\mathsf{N}}}^{t}.$ ), (P) and (LOD) are all cenvector problems solved with a tributed Power iteration implementation [68].

Datasets: CC
OpenImages [3
Evaluation N
boxes in single

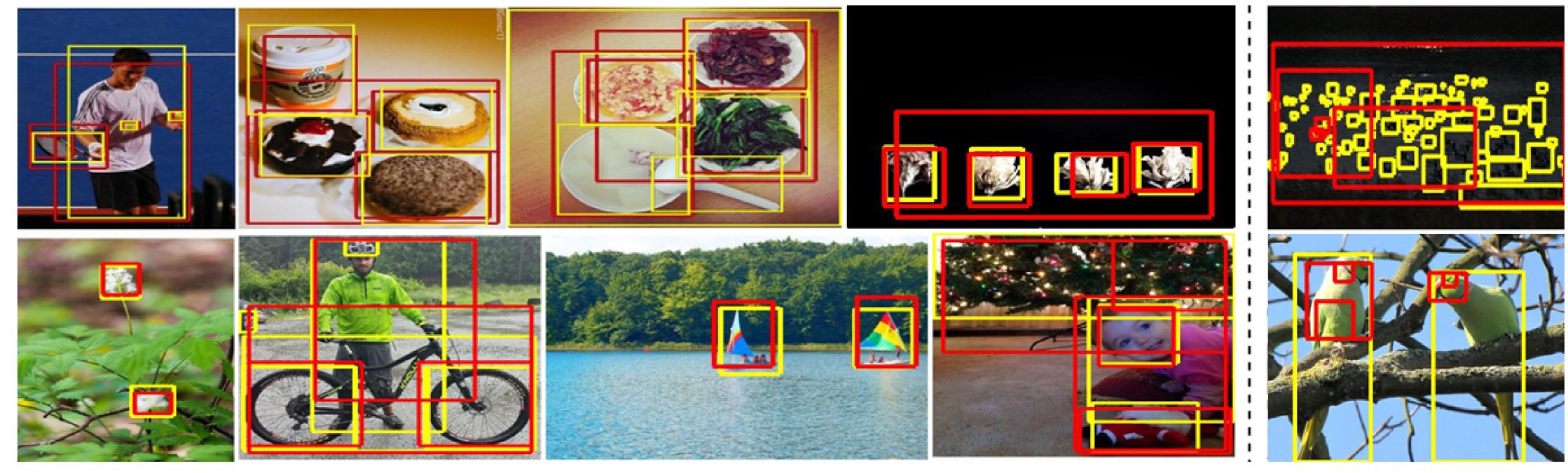
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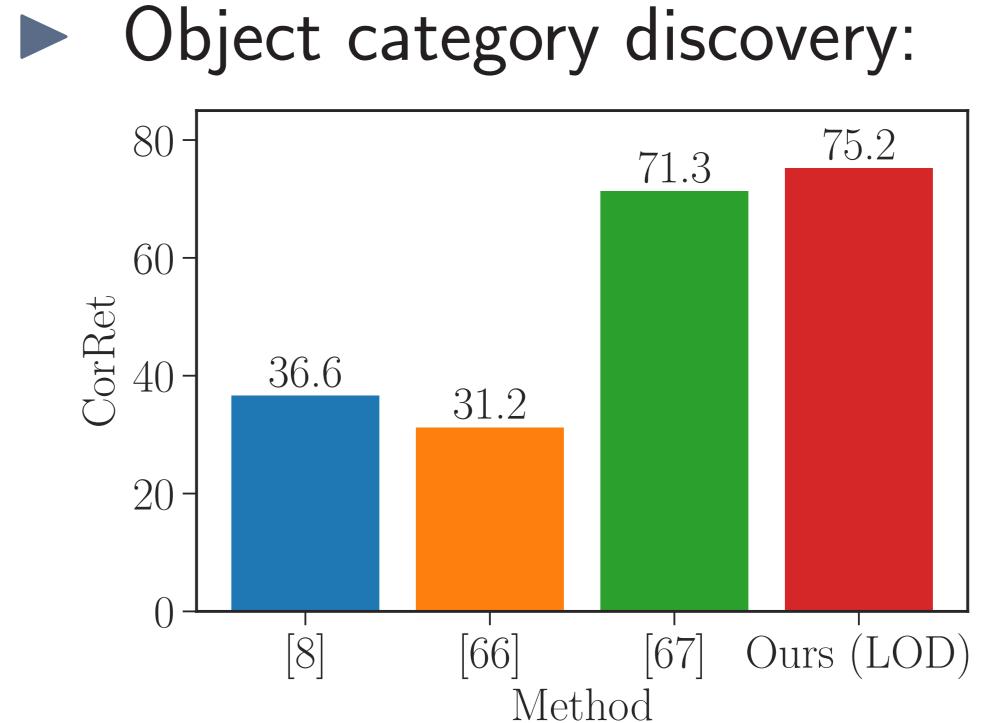
Quantitative comparison to the state of the art:												
		Single-object			Multi-object							
Method		CorLoc (↑)			AP50 (↑)			AP@[50:95] (↑)				
	C20K	C120K	Op50K	Op1.7N	1C20K	C120K	Op50K	Op1.7N	1C20K	C120K	Op50K	Op1.7M
EB [83]	28.8	29.1	32.7	32.8	4.86	4.91	5.46	5.49	1.41	1.43	1.53	1.53
Wei [71]	38.2	38.3	34.8	34.8	2.41	2.44	1.86	1.86	0.73	0.74	0.6	0.6
Kim [32]	35.1	34.8	37.0	_	3.93	3.93	4.13	_	0.96	0.96	0.98	_
Vo [67]	48.5	48.5	48.0	47.8	5.18	5.03	4.98	4.88	1.62	1.6	1.58	1.57
Ours (LOD+Se	lf) 41.1	42.4	49.5	49.4	4.56	4.90	6.37	6.28	1.29	1.37	1.87	1.86
Ours (LOD)	48.5	48.6	48.1	47.7	6.63	6.64	6.46	6.28	1.98	2.0	1.88	1.83
Dun time comparison:												

Kun time comparison:



### Sample qualitative results:









### EXPERIMENTAL RESULTS

COCO trainval [42] (120k images), COCO20K (20k images), [35] (1.7 million images), Open50K (50k images).

Metrics: correct localization (CorLoc, precision of returned boxes in single-object setting) and average precision (AP).

Number of images (in thousands)

Dataset LOD [75] [82] [14] [73] [74] [31] [33 SIVAL1 97.4 89.0 95.3 80.4 39.3 38.0 27.0 45.0 SIVAL2 99.0 93.2 84.0 71.7 40.0 33.3 35.3 33.3 SIVAL3 88.3 88.4 74.7 62.7 37.3 38.7 26.7 41.3 SIVAL4 97.7 87.8 94.0 86.0 33.0 37.7 27.3 53.0 SIVAL5 94.3 92.7 75.3 70.3 35.3 37.7 25.0 48.3 Average **95.3** 90.2 84.7 74.2 37.0 37.1 28.3 44.2